Green's-function Monte Carlo for lattice fermions: Application to the *t*-*J* model

C. Stephen Hellberg

Center for Computational Materials Science, Naval Research Laboratory, Washington, D.C. 20305

Efstratios Manousakis

Department of Physics and MARTECH, Florida State University, Tallahassee, Florida 32306-3016

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We develop a general numerical method to study the zero-temperature properties of strongly correlated electron models on large lattices. The technique, which resembles Green's-function Monte Carlo, projects the ground-state component from a trial wave function with no approximations. We use this method to determine the phase diagram of the two-dimensional t-J model, using the Maxwell construction to investigate electronic phase separation. The shell effects of fermions on finite-sized periodic lattices are minimized by keeping the number of electrons fixed at a closed-shell configuration and varying the size of the lattice. Results obtained for various electron numbers corresponding to different closed shells indicate that the finite-size effects in our calculation are small. For any value of interaction strength, we find that there is always a value of the electron density above which the system can lower its energy by forming a two-component phase separated state. Our results are compared with other calculations on the t-J model. We find that the most accurate results are consistent with phase separation at all interaction strengths.

I. INTRODUCTION

Correlated quantum many-body systems have provided a host of new phenomena such as new states of matter, new forms of ordering transitions, etc. These phenomena are the result of the appearance of fundamentally new relevant degrees of freedom which emerge as a coherent superposition of the underlying degrees of freedom of the many variable system. Once one identifies the important degrees of freedom, these degrees of freedom can be treated by analytical or semianalytical techniques which are variants of generalized perturbation expansions around the defining framework. The problem which arises is that such frameworks cannot be imagined before hand unless there are hints from either experiment or numerical studies of models correctly capturing the dynamics of more basic degrees of freedom which, at first sight, seem featureless.

Several such models on a discrete lattice exist and a variety of numerical techniques are at our disposal to use.¹ Exact diagonalization techniques suffer from the fact that the dimensionality N_H of the Hilbert space grows exponentially with system size N_s (number of sites). Taking into account all the symmetries of the problem can reduce the size of the invariant subspaces to smaller size N_R (which may be a few orders of magnitude smaller than N_H). However, the largest possible size increases only with the logarithm of the ratio of N_H/N_R . In particular, most interesting quantities scale with the linear dimension of the system which scales with $\left[\ln(N_H/N_R)\right]^{1/d}$ where d is the dimensionality of the problem. Renormalization-group approaches, such as the densitymatrix renormalization-group technique,² have been very successful in one dimension but there are significant limitations in higher dimensions.

Attractive alternatives seem to be stochastic methods such as quantum Monte Carlo which can give information about larger size systems. Many interesting problems, however, involve fermionic degrees of freedom. If one attempts a simulation of fermions at low temperature one encounters the so-called fermion sign problem. Namely, one needs to define configurations which carry a phase (a positive or negative sign) along with their statistical weights, a reflection of the transformation property of the fermion wave function under particle permutation. In the computation of many quantities of interest, such as the energy, the "positive" and the "negative" configurations give nearly opposite contributions, leading to wildly fluctuating weights. The negativesign problem causes the statistical fluctuations to diverge exponentially with increasing system size for fixed density.

The Green's-function Monte Carlo (GFMC) method has been successfully applied to lattice spin systems, in particular to the square lattice spin-1/2 Heisenberg quantum antiferromagnet.^{1,3–7} In this case, through the Marshall-sign transformation, the problem can be mapped to a hard-core boson problem which presents no sign problem and solved accurately on large systems.

An approximate method to deal with the sign problem in fermionic systems is the fixed node (FN) approximation.^{8,9} This approach projects a trial state onto the best variational state with the same nodal structure, thus controlling the statistical fluctuations. The FN approximation has been used for lattice fermion systems also.^{10–12}

The GFMC method for lattice fermions without the fixed node approximation has been applied to one-dimension systems.¹³ In two dimensions it has been applied to the t-J model in the limits of small numbers of electrons¹⁴ or holes.^{15,16}

In this paper, we present an efficient implementation of GFMC for lattice fermions at arbitrary densities of electrons or holes. We demonstrate the utility of the method in the case of the two-dimensional t-J model. The method projects a trial wave function onto the lowest energy eigenstate that it overlaps. If the trial state overlaps the ground state, the pro-

PRB <u>61</u>

11 787

jection yields the ground state. The projection becomes statistically more accurate as the ground-state component of the trial state increases relative to the excited-state components. Results obtained for the t-J model with this method have been published by the authors.¹⁷ In this paper we present the general method and in addition, our results for the t-J model are presented in detail and compared with other recent calculations.

The *t*-*J* model is thought to contain some important aspects of the environment in the copper-oxide superconductors. For instance, the calculated single-hole spectrum¹⁸ is in agreement with the results of the photoemission data.¹⁹ The model gives rise to a two-hole bound state¹⁵ with the $d_{x^2-y^2}$ symmetry which is the believed symmetry of the superconducting state in these materials. In addition, Emery, Kivelson, and Lin^{20} (EKL) suggested that the cuprates are near an electronic phase-separation (PS) instability which is prevented by the long-range part of the Coulomb interaction. In the phase-separated state, the holes cluster together with a certain density of electrons, leaving the rest of the system in an antiferromagnetic state with no holes. Phase separation in the t-J model has been studied by a number of techniques which seem to be giving conflicting conclusions.^{17,21–27} High-temperature series expansions 23,24 and some studies on small systems²⁵ indicated that phase separation does not occur at the physical region for the cuprates, namely J/t $\sim 0.3-0.4$, while other studies on small systems^{20,21} found this region was unstable to phase separation. Using the GFMC method presented in this paper, Hellberg and Manousakis¹⁷ found that the t-J model has a region of phase separation at all interaction strengths.

In recent work, Calandra, Becca, and Sorella²⁷ (CBS) emphasize that the phase separated region does not extend below $J/t \leq 0.4$. In addition, the density-matrix renormalization-group method has been also applied to this problem by White and Scalapino^{28,29} (WS) who find that the ground state of the *t*-*J* model on the square lattice is characterized by stripes.

In the last section of this paper, we compare our results to those of CBS and WS, concluding that the physical region of the model is very close to or inside of a PS instability. Namely, the early conclusions that *the physical region of the* t-J model is far from the critical J_c for phase separation, are largely invalid.

II. NUMERICAL METHOD

Even though our formalism is general and can be applied to other lattice fermion models, we shall use the example of the t-J Hamiltonian on a two-dimensional square lattice. This model in itself is a nontrivial extension of the square lattice Heisenberg antiferromagnet¹ where GFMC was first applied on a lattice model.

The *t*-*J* model is written in the subspace with no doubly occupied sites as

$$H = -t \sum_{\langle i,j \rangle \sigma} \left(c_{i\sigma}^{\dagger} c_{j\sigma} + \text{H.c.} \right) + J \sum_{\langle i,j \rangle} \left(\mathbf{S}_{i} \cdot \mathbf{S}_{j} - \frac{n_{i} n_{j}}{4} \right).$$
(1)

Here $\langle i,j \rangle$ enumerates neighboring sites on a square lattice, $c_{i\sigma}^{\dagger}$ creates an electron of spin σ on site $i, n_i = \sum_{\sigma} c_{i\sigma}^{\dagger} c_{i\sigma}$, and \mathbf{S}_i is the spin- $\frac{1}{2}$ operator.

A. Details of the projection

We take a trial wave function Ψ and project it onto the ground state by generating a series of increasingly accurate approximants to the ground state labeled by integers $|m\rangle = (H-W)^m |\Psi\rangle$. Here *H* is the Hamiltonian and *W* is an appropriately chosen numerical constant.^{30–33}

We may expand the trial state in terms of the exact eigenstates:

$$|\Psi\rangle = a_0 |\Phi_0\rangle + a_1 |\Phi_1\rangle + \cdots, \qquad (2)$$

where $|\Phi_0\rangle$ is the ground state, $|\Phi_1\rangle$ is the first excited state, and the a_i 's are the expansion coefficients. Rewriting the projected states in this way, we see

$$|m\rangle = (H - W)^m |\Psi\rangle \tag{3}$$

$$= a_0 (E_0 - W)^m |\Phi_0\rangle + a_1 (E_1 - W)^m |\Phi_1\rangle + \cdots$$
 (4)

$$\times \left\{ |\Phi_0\rangle + \frac{a_1}{a_0} \left(\frac{E_1 - W}{E_0 - W}\right)^m |\Phi_1\rangle + \cdots \right\},\tag{5}$$

where E_i is the energy of the *i*th eigenstate. So $|m\rangle$ approaches the ground state for large *m* provided

$$|E_{i>0} - W| < |E_0 - W| \tag{6}$$

for all excited state energies $E_{i>0}$. The projection can be formulated in this simple way because eigenvalues of lattice Hamiltonians are bounded from below *and* above. Continuum problems require a different form for the projection operator.^{34,35} In what follows, we assume the offset constant *W* is incorporated in the Hamiltonian.

From Eq. (5) we see rate of convergence with m is governed by the overlap of the trial state with the ground state and the energy of the lowest excited state overlapping the trial state. In Sec. II D, we describe the steps taken to insure fast convergence.

To calculate ground-state expectation values of an arbitrary operator A, we take the large m limit of

$$\frac{\langle \Phi_0 | A | \Phi_0 \rangle}{\langle \Phi_0 | \Phi_0 \rangle} = \lim_{m \to \infty} \frac{\langle m | A | m \rangle}{\langle m | m \rangle}.$$
(7)

For large values of *m*, we cannot evaluate H^m directly. The number of position-space states generated diverges exponentially with the power *m*, so we calculate H^m by a stochastic method similar to Neumann-Ulam matrix inversion.³⁶ We decompose *H* into a product of a transition probability $p_{\alpha\beta}$ to make a transition from state α to state β and a residual weight $w_{\alpha\beta}$ as

$$H_{\alpha\beta} = p_{\alpha\beta} w_{\alpha\beta}, \qquad (8)$$

where

$$\sum_{\beta} p_{\alpha\beta} = 1, \quad p_{\alpha\beta} \ge 0. \tag{9}$$

To evaluate

$$\langle \alpha_0 | H^m | \alpha_m \rangle = \sum_{\alpha_1, \dots, \alpha_{m-1}} \langle \alpha_0 | H | \alpha_1 \rangle$$
$$\times \langle \alpha_1 | H | \alpha_2 \rangle \cdots \langle \alpha_{m-1} | H | \alpha_m \rangle (10)$$

stochastically, we average over *m*-step random walks $\alpha_0 \rightarrow \alpha_1 \rightarrow \cdots \rightarrow \alpha_{m-1} \rightarrow \alpha_m$, where each α_i is a position space state, giving each walk the accumulated weight

$$W(\alpha_0, \alpha_1, \dots, \alpha_m) = w_{\alpha_0 \alpha_1} w_{\alpha_1 \alpha_2} \cdots w_{\alpha_{m-1} \alpha_m}.$$
 (11)

The probability of the walk $\alpha_0 \rightarrow \alpha_1, \ldots \rightarrow \alpha_m$ is

$$P(\alpha_0, \alpha_1, \dots, \alpha_m) = p_{\alpha_0 \alpha_1} p_{\alpha_1 \alpha_2} \cdots p_{\alpha_{m-1} \alpha_m}.$$
 (12)

Thus it follows that

$$\langle \alpha_0 | H^m | \alpha_m \rangle = \sum_{\alpha_1, \dots, \alpha_{m-1}} W(\alpha_0, \alpha_1, \dots, \alpha_m)$$
 (13)

for a large number of walks guided by the probability (12).

B. Importance sampling

The Monte Carlo sum (13) is evaluated most efficiently using importance sampling. We cannot use the trial state as a guiding function for the random walk, since the guiding function must be positive for all allowed states. Labeling our guiding function Ψ^G , we let

$$p_{\alpha\beta} = \frac{1}{z_{\alpha}} \frac{\Psi_{\beta}^{G}}{\Psi_{\alpha}^{G}} H_{\alpha\beta}, \qquad (14)$$

where the normalization is simply the local energy:

$$z_{\alpha} = \sum_{\beta} \frac{\Psi_{\beta}^{G}}{\Psi_{\alpha}^{G}} H_{\alpha\beta}.$$
 (15)

Defined in this way, Eq. (14) satisfies Eq. (9), and the residual weight is

$$v_{\alpha\beta} = z_{\alpha} \frac{\Psi^G_{\alpha}}{\Psi^G_{\beta}},\tag{16}$$

resulting in the accumulated weight for the m-step walk given by Eq. (11).

For an antisymmetric trial wave function Ψ^T , the standard algorithm to evaluate

$$\langle \Psi^{T} | H^{m} | \Psi^{T} \rangle = \sum_{\alpha, \beta} \Psi^{T*}_{\alpha} \langle \alpha | H^{m} | \beta \rangle \Psi^{T}_{\beta}, \qquad (17)$$

where $\Psi_{\alpha}^{T*} = \langle \Psi^T | \alpha \rangle$, is to generate a set of *M* initial states $\{\alpha_i\}$ with probabilities proportional to $Q_{\alpha_i} \propto |\Psi_{\alpha_i}^T|^2$ using Metropolis sampling as in variational Monte Carlo. At each initial state $|\alpha_i\rangle$, we start an *m*-step random walk, ending in the state $|\beta_i\rangle$. For large *M*,

$$\langle \Psi^T | H^m | \Psi^T \rangle \rightarrow \frac{1}{M} \sum_{i=1}^M \frac{\Psi_{\alpha_i}^{T*} W(\alpha_i, \dots, \beta_i) \Psi_{\beta_i}^T}{Q_{\alpha_i}}.$$
 (18)

C. An efficient approach

The standard algorithm is inefficient since a random walk in configuration space of length *m* must be generated for each term in the sum (18). The details of the intermediate states are thrown away. The expectation value $\langle \Psi | H^m | \Psi \rangle$ can be evaluated more efficiently if the generation of the initial states $\{\alpha_i\}$ is combined with the generation of the random walks. In the random walk, new states are chosen with a probability given by Eq. (14). After a large number of steps, these states are distributed with a probability

$$Q_{\alpha} \propto z_{\alpha} [\Psi_{\alpha}^{G}]^{2} \tag{19}$$

which is derived by solving the "detailed balance" condition

$$Q_{\alpha}p_{\alpha\beta} = Q_{\beta}p_{\beta\alpha}, \qquad (20)$$

where $p_{\alpha\beta}$ is the probability to make a transition from configuration α to β given by Eq. (14), and Q_{α} is the probability to visit a state $|\alpha\rangle$.³⁷ Thus we may use states generated in the *m*-step random walk as initial states for new *m*-step random walks.

For maximum efficiency, we use every state generated as the starting point for a new walk, so at each step we calculate different stages of *m* walks simultaneously. We simply generate one very long random walk using the probability (14). At each step in the walk, we look *m* steps into the past to evaluate an element of Eq. (18). The computer time needed to calculate a given number of observations of $\langle H^m \rangle$ is independent of *m*. An additional advantage is that since only one long random walk is generated, we may calculate all different powers *m* in parallel. The fundamental observation becomes

$$\langle \Psi^{T} | H^{m} | \Psi^{T} \rangle = \frac{1}{M} \sum_{i=1}^{M} \frac{\Psi_{\alpha_{i-m}}^{T*} W(\alpha_{i-m}, \dots, \alpha_{i}) \Psi_{\alpha_{i}}^{T}}{z_{\alpha_{i-m}} |\Psi_{\alpha_{i-m}}^{G}|^{2}}.$$
(21)

The method is easily generalized to evaluate the expectation value $A_m \equiv \langle \Psi | H^m A H^m | \Psi \rangle$ for any *diagonal* operator A, such as the density or spin structure factors $n_i n_j$ and $S_i^z S_j^z$. At each stage in the walk, we look m steps into the past to obtain the expectation value of $\langle A \rangle$ and 2m steps into the past to calculate the accumulated weight. By summing M observations from a walk, we find

$$A_{m} = \frac{1}{M} \sum_{i=1}^{M} \frac{\Psi_{\alpha_{k}}^{T*} W(\alpha_{k}, \dots, \alpha_{i}) \Psi_{\alpha_{i}}^{T}}{z_{\alpha_{k}} |\Psi_{\alpha_{k}}^{G}|^{2}} \langle \alpha_{j} | A | \alpha_{j} \rangle, \quad (22)$$

where j = i - m and k = i - 2m.

The speed of convergence of the procedure with power *m* is determined by the ratio $R = |E_1 - W|/|E_0 - W| < 1$, where E_1 is the energy of the first excited state overlapping the trial state. Since this gap is caused by the finite size of the system, we generally calculated powers of the Hamiltonian up to several times the linear system size.

D. Trial wave functions

Care is needed to choose a trial state with maximal overlap with the true ground state. We restrict ourselves to total spin singlet states with zero momentum and try to write a very arbitrary form yielding a good initial guess throughout the phase diagram.

We use a Jastrow resonating-valence-bond (RVB) wave function for the trial state, written

$$\Psi^{T} = \prod_{i < j, \sigma, \sigma'} f(\mathbf{r}_{i, \sigma} - \mathbf{r}_{j, \sigma'}) | \text{RVB} \rangle$$
$$= \prod_{i < j, \sigma, \sigma'} f(\mathbf{r}_{i, \sigma} - \mathbf{r}_{j, \sigma'}) P_{N} \prod_{\mathbf{k}} (u_{\mathbf{k}} + v_{\mathbf{k}} c_{\mathbf{k}\uparrow}^{\dagger} c_{-\mathbf{k}\downarrow}^{\dagger}) | 0 \rangle,$$
(23)

where $c_{\mathbf{k}\sigma}^{\dagger}$ is the usual Fermion creation operator and P_N projects the state onto the subspace with the number of particles fixed to be *N*.

It is important that the Jastrow factor f correlate *all* pairs of particles independent of spin, yielding a correlated state that is still a total spin singlet. If we allow different Jastrow factors for like and unlike spins, we could usually reduce the

variational energy of the trial state. However, the resultant state would be a superposition of many spin states and in general would overlap excited states with nonzero spin *closer* in energy to the ground state than the lowest spin zero excited state, resulting in *slower* projection than a singlet trial state with higher variational energy.

We write the determinantal part of the trial state in the usual way.³⁸ The ratio $a_{\mathbf{k}} \equiv v_{\mathbf{k}}/u_{\mathbf{k}}$ is the physical quantity, and, assuming $a_{\mathbf{k}} \equiv a_{-\mathbf{k}}$, we define $a(\mathbf{r})$ as its Fourier transform:

$$a(\mathbf{r}) = \sum_{\mathbf{k}} a_{\mathbf{k}} \cos(\mathbf{k} \cdot \mathbf{r}).$$
(24)

Then

$$|\mathbf{R}\mathbf{V}\mathbf{B}\rangle = P_{N}\prod_{\mathbf{k}} (u_{\mathbf{k}} + v_{\mathbf{k}}c_{\mathbf{k}\uparrow}^{\dagger}c_{-\mathbf{k}\downarrow}^{\dagger})|0\rangle$$
$$= \left(\sum_{\mathbf{r}_{i\uparrow}, \mathbf{r}_{j\downarrow}} a(\mathbf{r}_{i\uparrow} - \mathbf{r}_{j\downarrow})c_{\mathbf{r}_{i\uparrow}}^{\dagger}c_{\mathbf{r}_{j\downarrow}}^{\dagger}\right)^{N/2}|0\rangle \qquad (25)$$

can be written as the $(N/2) \times (N/2)$ determinant

$$|\mathbf{D}| = \begin{vmatrix} a(\mathbf{r}_{1\uparrow} - \mathbf{r}_{1\downarrow}) & a(\mathbf{r}_{1\uparrow} - \mathbf{r}_{2\downarrow}) & \cdots & a(\mathbf{r}_{1\uparrow} - \mathbf{r}_{(N/2)\downarrow}) \\ a(\mathbf{r}_{2\uparrow} - \mathbf{r}_{1\downarrow}) & a(\mathbf{r}_{2\uparrow} - \mathbf{r}_{2\downarrow}) & \cdots & a(\mathbf{r}_{2\uparrow} - \mathbf{r}_{(N/2)\downarrow}) \\ \vdots & \vdots & \ddots & \vdots \\ a(\mathbf{r}_{(N/2)\uparrow} - \mathbf{r}_{1\downarrow}) & a(\mathbf{r}_{(N/2)\uparrow} - \mathbf{r}_{2\downarrow}) & \cdots & a(\mathbf{r}_{(N/2)\uparrow} - \mathbf{r}_{(N/2)\downarrow}) \end{vmatrix}$$
(26)

in position space.

In this form, $|RVB\rangle$ spans a broad class of Fermion wave functions. A Fermi-liquid state corresponds to

$$a_{\mathbf{k}} = \begin{cases} 1 & \mathbf{k} \in \text{Fermi sea} \\ 0 & \text{otherwise} \end{cases}$$
(27)

while by allowing other choices for a_k , the wave function can describe a pairing state, which may be *s* wave, *d* wave, or something more general.

E. Guiding function

We are tempted to use the magnitude of the trial state as our guiding wave function, but this would be a serious mistake. By construction, the sites of a periodic lattice lie at high-symmetry points, and the nodes of a fermion wave function also respect these symmetries. One finds $\langle \Psi_{\alpha}^{T} | \alpha \rangle$ = 0 for a significant fraction of states in the Hilbert space not violating the Pauli exclusion principle. Since

$$\langle \Psi^{T} | H^{p} | \Psi^{T} \rangle = \sum_{\alpha_{0}, \dots, \alpha_{n}} \langle \Psi^{T}_{\alpha_{0}} | H | \alpha_{1} \rangle \cdots \langle \alpha_{m-1} | H | \Psi^{T}_{\alpha_{m}} \rangle,$$
(28)

where the intermediate sums over $\alpha_1, \alpha_2, \ldots, \alpha_{n-1}$ span the *complete* Hilbert space, we must guide with a positive function.

Every guiding function that samples the complete Hilbert space will yield correct results. Our challenge is to pick a function that minimizes the statistical fluctuations of our output. The guiding function cannot ameliorate the sign problem in Eq. (21). We can, however, choose a function to reduce the fluctuations in $|\Psi^T|/|\Psi^G|$. We define

$$\Psi^G \equiv \max\{|\Psi^T|, c\Psi^B\},\tag{29}$$

where Ψ^B is a positive function, typically a good variational state of the bosonic Hamiltonian. We take Ψ^B to be a spindependent Jastrow function.¹⁴ This is similar to a choice used in continuum problems, but on a discrete lattice, it is not necessary to match the first derivatives as in the continuum.³⁹

We rescale *c* so the effective number of configurations contributing to the norm is approximately $N \approx 1/L$ for an $L \times L$ system.⁴⁰ This guiding function is shown schematically in Fig. 1.

For the guiding function, we use the Jastrow-pairing function



FIG. 1. Schematic behavior of the guiding function near a node. The squares and diamonds are the trial state and its negative, respectively. The circles are the bosonic state, and the guiding function, $\Psi^G = \max\{|\Psi^T|, c\Psi^B\}$, is shown by the filled symbols. *r* represents a single coordinate of one electron.

$$\Psi^{B} = \prod_{i < j} f(\mathbf{r}_{i\uparrow} - \mathbf{r}_{j\uparrow}) \prod_{i < j} f(\mathbf{r}_{i\downarrow} - \mathbf{r}_{j\downarrow}) \prod_{i,j} g(\mathbf{r}_{i\uparrow} - \mathbf{r}_{j\downarrow})$$
(30)

of Bose spin- $\frac{1}{2}$ particles (i.e., two kinds of bosons: up bosons and down bosons). We have chosen this function to mimic the physics of the fermion state as closely as possible without having nodes. Since it is not important to guide with a spin singlet function, we use a more arbitrary spin-dependent Jastrow factor where like spin particles are correlated differently than opposite spin particles.

F. Walking through the nodes

To evaluate the determinantal wave function, at the beginning of the random walk we calculate the determinant, an $O(N^3)$ operation for a $N \times N$ determinant, and its inverse, also an $O(N^3)$ operation. Each kinetic step in the walk changes either a row or column of the determinant, while superexchange changes both a row and column. Ceperley, Chester, and Kalos⁴¹ showed that the determinant and inverse may be updated after such moves efficiently in $O(N^2)$ steps. This so called "inverse update" works well for variation Monte Carlo or fixed node Monte Carlo, but it cannot be used directly with GFMC on a lattice since the random walk steps directly on nodes for a significant fraction of steps. In a reasonably dense system, we find as many as 1/3 of the steps land on nodes. On a node, the matrix is singular, the determinant is zero, and the inverse is undefined. Recalculating the determinant and inverse after walking through a node will cause the running time to scale as $O(N^3)$.

We developed an efficient $O(N^2)$ technique to hop over nodes without recalculation of the determinant or inverse. The essence of the method is this: When the random walk generated by the guiding function hits a state or series of states where the determinant of the trial function vanishes, we generate a "detour" walk around the region where the matrix is singular, rejoining the guiding walk when the determinant is nonzero again. We stress that the real random walk goes though the node, the detour walk is a fictitious one which is used only to calculate the determinant and its inverse. It serves only as a calculational tool for the inverse update. The details of this detour-walk approach of evaluating the determinant and its inverse when the walk went through a node are explained in Appendix A. Since we often land on a node where the inverse of the matrix (26) is not defined, it is difficult to calculate the probabilities $p_{\alpha\beta}$ [Eqs. (14) and (15)] for the random walk we defined earlier. When we are on a node with $\Psi_{\alpha}^{T}=0$, we need to choose the next step of the walk from the various possible β states. Therefore we need to calculate z_{α} with Eq. (15). Since we are on the node, calculating each Ψ_{β}^{T} requires a detour walk which in itself takes N^{2} steps. Thus the calculation of z_{α} is an $O(N^{3})$ process, whereas when $\Psi_{\alpha}^{T} \neq 0$ it is an $O(N^{2})$ process. Therefore we make the following adjustments so that each step is an $O(N^{2})$ process. We define

$$p_{\alpha\beta} = \frac{1}{z_{\alpha}} f_{\alpha\beta} H_{\alpha\beta}, \qquad (31)$$

$$z_{\alpha} = \sum_{\beta} f_{\alpha\beta} H_{\alpha\beta}, \qquad (32)$$

where if $\Psi_{\alpha}^{T} \neq 0$

$$f_{\alpha\beta} = \begin{cases} \Psi_{\beta}^{G}/\Psi_{\alpha}^{G} & \text{if } \Psi_{\beta}^{T} \neq 0\\ c^{2}\Psi_{\alpha}^{B}\Psi_{\beta}^{B}/|\Psi_{\alpha}^{G}|^{2} & \text{if } \Psi_{\beta}^{T} = 0 \end{cases}$$
(33)

and if $\Psi_{\alpha}^{T}=0$,

$$f_{\alpha\beta} = \frac{\Psi^B_\beta}{\Psi^B_\alpha}.$$
 (34)

It is easy to show that detailed balance is obeyed by these definitions. The advantage of using these probabilities is that if $\Psi_{\alpha}^{T}=0$, then calculating Ψ_{β}^{T} for all β with $H_{\alpha\beta}\neq 0$ not required. Since we do not have the inverse matrix of the trial function's determinant in state α , such a calculation would be computationally very expensive.

Calculating Ψ^B_{β} is always easy due to the simple form of Eq. (30), but Ψ^T_{β} is more difficult. The kinetic operator moves a single electron, so Ψ^T_{β} may be calculated in O(N)steps since the inverse need not be updated. The superexchange operator moves two electrons and changes both a row and column of Eq. (26). Updating the inverse to calculate this term requires $O(N^2)$ steps, which would cause the overall algorithm to scale as $O(N^3)$ for the system. In Appendix B we derive an O(N) method of calculating superexchange.

G. Trial state optimization

It is important that we start the GFMC with good trial and guiding states. In this section, we describe our method for optimizing these functions.

In continuum systems, one usually assumes a functional form for the trial and guiding functions and optimizes a function of the energy to find the best variational parameters. On a lattice, there are only a finite number of distances \mathbf{r} or equivalently wave vectors \mathbf{k} in any given simulation, so we allow the functions in Eqs. (23) and (30) to have a parameter describing each distance or wave vector not related by symmetry.

For the Jastrow and position space pair factors, $f(\mathbf{r})$ and $g(\mathbf{r})$, we apply all rotational and mirror symmetries. Translational symmetry is always assumed. However, we insist only on the mirror symmetries about the axes for the Fer-

mion pairing field a_k , so the function may be any linear combination of an *s* and $d_{x^2-y^2}$ pairing state. The mirror symmetry excludes d_{xy} symmetry. For a 20×20 lattice, we have 172 parameters for the trial state and 192 parameters for the guiding function with the pairing term.

We tried optimizing several functions of the energy, but found minimizing the variance of the local energy to be the most robust.⁴² We generate a set of configurations $\{\alpha_1, \alpha_2, \ldots, \alpha_m\}$ distributed according to a weight w_{α_i} . The configurations remain the same throughout the minimization procedure. We minimize the function

$$\sigma^{2} = \frac{\sum_{i=1}^{m} [H\Psi_{\alpha_{i}}^{T}/\Psi_{\alpha_{i}}^{T} - E]^{2} |\Psi_{\alpha_{i}}^{T}|^{2}/w_{\alpha_{i}}}{\sum_{i=1}^{m} |\Psi_{\alpha_{i}}^{T}|^{2}/w_{\alpha_{i}}},$$
 (35)

where E is a guess for the ground-state energy that we determine self-consistently. We use the same function to optimize both our trial and guiding functions.

With a finite random walk, the calculation of the energy in Eq. (35) uses many more states than the calculation of the norm. Occasionally, this created instabilities, which we cured by deriving another way of calculating the norm using all the neighbors in the random walk. We may write

$$\langle \Psi | \Psi \rangle = \sum_{\alpha} |\Psi_{\alpha}|^2 \tag{36}$$

$$=\sum_{\alpha} \left(|\Psi_{\alpha}|^{2} (1-A_{\alpha}) + B_{\alpha} \sum_{\beta \in \{H_{\alpha}\}} |\Psi_{\beta}|^{2} \right), \qquad (37)$$

where $\{H_{\alpha}\}$ is the set of all states neighboring $|\alpha\rangle$ by application of the Hamiltonian. We see Eq. (37) follows from Eq. (36) if we choose $B_{\alpha} = C$ and $A_{\alpha} = CN_{\alpha}$ for some constant *C*, where N_{α} is the number of neighbors of $|\alpha\rangle$ where Ψ does not vanish. Since this version of the norm is calculated from all the states entering the energy, no factors in the numerator of Eq. (35) are absent from the denominator.

We calculate the effective number of configurations contributing to the normalization as

$$N_{\rm eff} = \left(\sum_{i=1}^{m} \frac{|\Psi_{\alpha_i}^{T}|^2}{w_{\alpha_i}}\right)^2 / \sum_{i=1}^{m} \frac{|\Psi_{\alpha_i}^{T}|^4}{w_{\alpha_i}^2}.$$
 (38)

This quantity approaches n if all states contribute equally to the integral and drops to 1 as one state begins to dominate.⁴⁰ We adjust the length of our random walks so N_{eff} is at least ten times the number of parameters being optimized.

We found that close to phase separation, the standard Metropolis algorithm develops a small acceptance ratio, and tends to stay in the same configuration for many steps. In order to sample more phase space quickly, we choose our configurations using the transition probability (14) where we take *H* to be the off-diagonal part of the Hamiltonian, ensuring a new configuration with each move. Thus the configurations are distributed according to the weight $w_{\alpha_i} = z_{\alpha_i} |\Psi_{\alpha_i}^G|^2$, where z_{α_i} is given by Eq. (15).

III. FITTING PROJECTION OUTPUT: INVERSE THEORY

A. Ground-state energy

The Green's-function Monte Carlo procedure takes a trial state and projects it onto the exact ground state. Its output consists of the observables for the energy

$$E^{(n)} = \langle \Psi | H^n | \Psi \rangle, \tag{39}$$

where the trial state $|\Psi\rangle$ has been normalized. For any operator A which does not commute with the Hamiltonian, using the present Monte Carlo method we calculate

$$a_{mn} = \langle \Psi | H^m A H^n | \Psi \rangle \tag{40}$$

as functions of powers of the Hamiltonian m and n.

These values converge to their ground-state values, except for a normalization factor, for large powers n and m. However, their statistical errors increase exponentially with increasing power due to the fermion sign problem.

To extract the most information on the ground state, we use the calculated observable for all powers less than some maximum power p_{max} . By including the highly converged small powers in the approach, we obtain much more accurate ground-state properties than can be obtained using the large powers alone. Let us consider the ground-state energy as an example to demonstrate the approach next.

Let us define the *T*-spectral function $c(\mathcal{E})$ with respect to the trial state $|\Psi\rangle$ as

$$c(\mathcal{E}) = \frac{1}{\pi} \lim_{\eta \to 0^+} \operatorname{Im} \langle \Psi | \frac{1}{\hat{H} - \mathcal{E} + i \eta} | \Psi \rangle$$
$$= \sum_i |\langle \Psi | \Phi_i \rangle|^2 \delta(\mathcal{E} - E_i).$$
(41)

To show this, one may expand the trial state in the exact eigenstates $|\Phi_i\rangle$ of \hat{H} as

$$|\Psi\rangle = \sum_{i=0} a_i |\Phi_i\rangle. \tag{42}$$

It is immediately evident from the above that the poles of $c(\mathcal{E})$ and of the exact spectral function are at the same energy values for those eigenstates $|\Phi_i\rangle$ which have nonzero overlap with the trial state $|\Psi\rangle$.

In order to proceed we discretize the energy interval using a fine mesh with ΔE , thus the energy takes discrete values E^*_m , $m=1,2,\ldots,M$ and the *T*-spectral function $c^*(E)$ is written as

$$c^{*}(E) = \sum_{m=1}^{M} c_{m}^{*} \delta(E - E^{*}_{m}), \qquad (43)$$

where $c_m^* \ge 0$ are non-negative real numbers. Thus this spectral function is thought of as a histogram, where in each fine slice of the histogram the value of the integral of c(E) multiplied by any function f(E) is simply $c_m^* f(E^*_m)$. We have used a mesh interval ΔE smaller than the finite-size gap between the lowest and the first excited state. Thus the contribution of the ground state to c^* is accurately represented

as a single delta-function peak. Namely, up to some $m = m_0$, $c_{m < m_0}^* = 0$, while $c_{m_0}^* > 0$ and $c_{m_0 < m < m_1}^* = 0$ and $c_{m_1}^* > 0$, etc.

Then the moments of the *T*-spectral function $c^*(E)$ can be calculated using both Eqs. (41) and (43) and thus we obtain

$$\langle \Psi | H^n | \Psi \rangle = \sum_{m=1}^M c_m^* E_m^{*n}, \qquad (44)$$

where $n = 0, 1, ..., p_{max}$. Since $p_{max} < M$, because typically $p_{max} = 40-60$ and M = 200-500, we have more unknowns (the c_m^* 's) than equations. However, the solution needs to satisfy the constraint $c_m^* \ge 0$ which limits the possible solutions. The optimal way to find the most likely solution is to minimize the χ^2 .

We gain very large computational savings by calculating all powers of H in parallel. However, this results in statistical correlations between results of different powers which must be treated accordingly.⁴³

We divide the measurements into M bins. The covariance matrix is defined

$$C_{ij} = \frac{1}{M-1} \left(\frac{1}{M} \sum_{k=1}^{M} (E_k^{(i)} - \bar{E}^{(i)}) (E_k^{(j)} - \bar{E}^{(j)}) \right), \quad (45)$$

where $E_k^{(i)}$ is the average of the *i*th power in the *k*th bin. For uncorrelated output, *C* is diagonal. With correlations, χ^2 is defined

$$\chi^{2} = \sum_{i,j} (\bar{E}^{(i)} - E^{(i)*}) C_{ij}^{-1} (\bar{E}^{(j)} - E^{(j)*}), \qquad (46)$$

where $E^{(i)*}$ is the fitting function given in terms of the coefficients c_m (which are to be determined by this minimization) by means of Eq. (44).

When *C* is diagonal, its inverse is trivial. For more general *C*, small errors in its components can result in large errors in its inverse, so it is important to calculate *C* accurately. Increasing the number of bins decreases the statistical error in *C* but increases the systematic error due to autocorrelations. To balance these two sources of error, we choose the number of measurements in each bin to be $n = M p_{\text{max}}$, where p_{max} is the maximum power of the Hamiltonian.⁴³ We calculate statistical errors with the bootstrap method.⁴⁴

Figure 2 gives a typical example for the *T*-spectral function $c^*(E)$ obtained from the calculation of the twodimensional *t-J* model. The lowest value of E^* where we have a delta-function peak gives the lowest eigenstate of *H* which is not orthogonal to the trial state. The value of the peak gives the square of the overlap of the lowest energy state to the trial state.

We have tested our method by comparing our results with exact results for the 4×4 size lattice with several electrons. In Fig. 3 we show the results for the energy as a function of the iteration for the case of ten electrons. Figure 4 shows a larger system.

The energy estimate defined by



FIG. 2. The *T*-spectral function of the full Hamiltonian. The lowest energy peak is at the lowest energy eigenstate of the system which is nonorthogonal to the trial state. The value of spectral weight is the square of the overlap of the true ground state to the initial trial state.

$$E_{p} = \frac{\langle \Psi | H^{p+1} | \Psi \rangle}{\langle \Psi | H^{p} | \Psi \rangle}$$
(47)

as a function of *p* is shown in Fig. 3 starting from the Jastrow-RVB value of the energy at m=0. Notice that with the length of the walk in configuration space used for this calculation, the error (which always grows exponentially) becomes annoyingly big for values of *p* not shown. The value of the energy obtained by the extrapolation method described in previous section is also shown. By using the information contained in all the powers of *H* up to p_{max} instead of the just the estimates of the energy at or just below p_{max} we obtain a much better estimate for the energy.



FIG. 3. The energy for ten electrons in a 4×4 lattice as a function of the power of the Hamiltonian. The value of the energy obtained by the extrapolation method described in this section is also shown.



FIG. 4. The energy for 50 electrons in a 7×8 lattice as a function of the power of the Hamiltonian. The value of the energy obtained by the extrapolation method described in previous section is also shown.

B. Other operators

For an arbitrary operator A, we have

$$\langle \Psi | H^{n} A H^{n} | \Psi \rangle = \sum_{i,j} (E_{i} E_{j})^{P} \langle \Psi | \Phi_{i} \rangle \langle \Phi_{i} | A | \Phi_{j} \rangle \langle \Phi_{j} | \Psi \rangle$$
$$= \int dE E^{2p} a(E), \qquad (48)$$

where the operator overlap function a(E) is given by

$$a(E) = \sum_{i,j} \delta(E + \sqrt{E_i E_j}) \langle \Psi | \Phi_i \rangle \langle \Phi_i | A | \Phi_j \rangle \langle \Phi_j | \Psi \rangle.$$
(49)

Following the approach for the energy *T*-spectral function, we can define a discrete overlap function



FIG. 5. The *T*-spectral function associated with the spinstructure function. Notice that the lowest energy peak is at the same energy as that of the energy *T*-spectral function. The value of spectral weight is related to the spin-structure function in a simple way.



FIG. 6. The spin-spin correlation function for ten electrons in a 4×4 lattice as a function of the power of the Hamiltonian. The value of the correlation obtained by the extrapolation method described in previous section is also shown.

$$a^{*}(E) = \sum_{i=0}^{M} \delta(E - E_{i}^{*})a_{i}^{*}.$$
(50)

Here the values of *E* where the *T*-spectral function $a^*(E)$ attains peaks are all possible geometric means $\sqrt{E_iE_j}$ of all the eigenenergies which correspond to eigenstates which have nonzero overlap with $|\Psi\rangle$ and they give nonzero matrix element of *A*. The lowest energy peak corresponds to the geometric mean of the ground-state energy with itself, i.e., $E_0 = \sqrt{E_0E_0}$, thus if the ground state is not degenerate it is uniquely specified. Here we also need to solve for all the a_i^* given that they obey the following p_{max} equations:

$$\langle \Psi | A | \Psi \rangle = \sum_{i=0}^{M} a_i^*,$$

$$\langle \Psi | HAH | \Psi \rangle = \sum_{i=0}^{M} (E_i^*)^2 a_i^*,$$

:

$$\langle \Psi | H^p A H^p | \Psi \rangle = \sum_{i=0}^{M} (E_i^*)^{2p} a_i^*.$$
(51)

Figure 5 gives a typical example for the spectral function $a^*(E)$ obtained for the spin-structure function $S(\pi/2, \pi/2)$ from the calculation of the two-dimensional the *t-J* model. Notice that the energy of the lowest peak is the energy of the lowest energy state having nonzero overlap with the trial state and which has nonzero matrix elements with the operator *A*. For the value of the peak, which is a_i^* , the expectation value of *A* can be calculated in a straightforward manner.

In principle, we can also extract information about the excited states along with the ground state. This possibility is indicated by the fact that we can see higher energy peaks in these spectral functions.

In Fig. 6 we compare our results for the spin-spin correlation function with that obtained by exact diagonalization of the 4×4 size system with ten electrons. Notice the fine scale used to be able to distinguish the difference between exact and extrapolated correlation functions.



FIG. 7. The ground-state energy per site at J=2.5t for 32 electrons. For clarity, the energies are shifted by a linear factor $-e_H n_e$. The circles with error bars show the energies calculated on lattices of dimensions 6×6 , 7×6 , ..., 28×28 . A sixth-order polynomial fit to the data is shown as the solid line, which is extended to the Heisenberg energy, the square at energy zero in this shifted plot. The dashed line shows the ground-state energy of the infinite system in the phase-separated region. We find the onset of phase separation occurs at $n_{ps}=0.296\pm0.004$, while the inverse compressibility vanishes at $n_{comp}=0.52\pm0.10$.

IV. RESULTS FOR THE TWO-DIMENSIONAL t-J MODEL

A. Maxwell construction: Phase separation

A number of methods to determine the phase separation boundary numerically have been used. In one-dimensional systems the divergence of the density structure factor at long wavelengths has been used.¹³ Divergence of the compressibility as determined from the second derivative of the energy with respect to electron or hole density was used successfully on the one-dimensional t-J model by calculating the energy for three differing densities.⁴⁵ In the onedimensional model, phase separation occurs between two regimes, one with no electrons while the other contains some electrons and some holes. For a finite system, electrons may tunnel through the vacuum, lowering the ground-state energy. For this reason, the inverse compressibility actually passes through zero and becomes slightly negative. This effect is a surface effect and vanishes in the limit of infinite system size.

In the one-dimensional *t-J* model, the compressibility diverges continuously at the transition point in contrast to the discontinuous transition in two dimensions.^{24,45} The behavior of the energy derivatives across the phase-separation boundary is discussed in Appendix C. We have verified that in one dimension, the Maxwell construction yields the same phase-separation boundary as that calculated using the inverse compressibility.

In the two-dimensional t-J model, the situation is more complicated. The Fermi surface can change dramatically with electron density for a given system size. These strong shell effects make accurate comparisons of energies calculated with different numbers of electrons impossible.

Many of the previous studies used a vanishing inverse compressibility as the criterion for the onset of phase separation.^{24,25} The compressibility, however, is not the proper observable to find the phase-separation boundary in the two-dimensional t-J model, where the transition is first order. It is true that the compressibility diverges in the region of phase separation, but it jumps discontinuously at the boundary with the uniform phase. Numerically, this discontinuity is difficult to see in even large finite systems due to the surface energy of the two coexisting phases. When one is in the region of the phase diagram where phase separation exists, then, the compressibility suffers strong finite-size effects because of the rather large surface energy of the two coexisting phases.

The ground-state energy as a function of electron density at J=2.5t for 32 electrons on a variety of system sizes is shown in Fig. 7. These finite systems necessarily constrain the electron density to be uniform on the length scales of the system size. We fit the discrete data to a polynomial $e(n_e)$, shown as the solid curve, in order to treat the energy as a continuous function of density. The dashed line, $e_{ps}(n_e)$, is a linear function that intersects the Heisenberg energy, e_H at electron density $n_e=1$ and intersects $e(n_e)$ tangentially at a density labeled n_{ps} .

It is straightforward to show that the ground state of the infinite system at a density $n_e > n_{ps}$ cannot be a uniform phase, because the energy of the uniform phase, $e(n_e)$, is higher than $e_{ps}(n_e)$ at the same density. This latter energy corresponds to the energy of a mixture of two phases, one at electron density $n_A = 1$ and the other at electron density $n_B = n_{ps}$. Therefore the infinite system phase separates into two regions with densities n_A and n_B , and its ground-state energy is given by $e_{ps}(n_e)$, the value of the dashed line at the average density of the system. This is known as the Maxwell construction.²⁰

The energy of the infinite system is given by the solid line in Fig. 7 for $n_e < n_{ps}$ and by the dashed line for $n_e > n_{ps}$. A difference between the Maxwell construction in Fig. 7 and that commonly used is that the density of one of the constituent phases, the Heisenberg phase at $n_e = 1$, lies at an extreme limit of the allowed density range. It is not possible to add electrons to the Heisenberg solid, which has one electron on every site, so while the dashed line is tangent to the fitting curve at $n_e = n_{ps}$, it is not at $n_e = 1$. If the t-J model did allow electron densities $n_{e} > 1$, then the intersection point of the solid and dashed lines would be shifted to higher densities where the curves could intersect tangentially. The dashed line might intersect the solid curve tangentially at the higher density point in this region. At any electron density in the range $n_{ns} < n_{e} < 1$, the system can reduce its energy from that of the uniform phase approximated by the fitting polynomial in Fig. 7, by separating into two regions with densities n_A $=n_{ps}$ and $n_B=1$, resulting in an energy given by the dashed line at the average density.

In order to be stable, the energy of the infinite system must be concave everywhere. Given the solid line in Fig. 7 and the allowed density range of the *t*-*J* model, the dashed line drawn in the figure is the only line possible to make the energy of the infinite system globally concave. This energy is given by the solid line for $n_e < n_{ps}$ and the dashed line for $n_e > n_{ps}$.

We never examined systems with densities $n_e \gtrsim 0.94$, so we cannot exclude the re-entrance of a homogeneous phase in this region. For such a phase to be stabilized, the solid curve in Fig. 7 would have to drop back below the dashed line in this density range. We never saw any indication of this possibility at any interaction strength. If a reentrant homogeneous phase did exist, the phase-separated region would persist at densities $n_e \le 0.94$. The new Maxwell line would lie slightly below the one drawn and would be tangent to the solid curve at both intersections, but the phaseseparated region would persist at densities $n_e \le 0.94$. We never saw any indication of this possibility at any interaction strength.

In the infinite system, the energy is a concave function of density with continuous first derivative. In the phaseseparated regime, the energy linearly interpolates between the energies of the two constituent phases. The inverse compressibility, the second derivative of the energy with respect to density, is positive in the uniform phase and zero where the system phase separates in the phase-separated regime. On a finite lattice, the surface effects of phase separation raise the energy, and we find the inverse compressibility calculated from different system sizes obtained from a fit to the discrete data remains positive even where the system is unstable to phase separation. For electron density n_e , the completely phase-separated energy per site, $e_{var} = e_H n_e$, is a variational upper bound to the phase-separated energy and is given by the completely phase-separated energy per site, $e_{var} = e_H n_e$. To show that, let N_e be the total number of electrons on a square lattice of N sites $(n_e = N_e/N < 1)$. Then, the total energy of the system is less or equal to $e_H N_e$ plus corrections which are negligible compared to this term in the thermodynamic limit. Let one constrain all the electrons to be close packed in one region of the lattice so that only the interaction term in Eq. (1) is operative. If the system



chooses not to do that, it means that the energy of any other chosen state is lower than the energy of this artificially imposed state. Thus the energy per site of the unconstrained system is lower than $e_H n_e$. The system is definitely unstable to phase separation at least where this variational energy is lower than the calculated energy per site of a finite system.

We fit the calculated energies in the uniform phase to a low-order polynomial. The energies in the uniform phase, where there is no surface energy, suffer much smaller finitesize effects than energies in the phase-separated regime. We extrapolate the tangent of the fitting function to electron density $n_e = 1$. At the phase-separation boundary, the tangent to the curve $e(n_e)$ extrapolates to the Heisenberg energy, $e(n_e=1)=e_H$. This construction ensures that the resulting infinite-system energy is concave everywhere. This is the only possible construction that ensures the resulting infinitesystem energy is concave everywhere.

B. Results at J = t

Using the Maxwell construction we have determined the boundary for phase separation of the t-J model. In these calculations we minimize the shell effects when varying the electron density by keeping the number of electrons fixed at a closed-shell configuration and changing the size of the lattice. In addition, we also choose the number of electrons to correspond to a closed-shell configuration. This choice eliminates possible degeneracies of states at the Fermi level. Such degeneracies might favor flatness of the energy as a function of density which might be mistaken for phase separation. When one varies the number of electrons keeping the system size fixed when adding an electron to a closed-shell configuration the kinetic energy goes up by a finite amount which leads to oscillatory behavior of the energy per site versus density. An additional (technical reason) for wanting to keep closed-shell configurations is that on a finite lattice it leads to an energy gap between the ground state and the first excited state which helps our projection method to converge.

In Fig. 8 we study the size dependence of the critical value of electron density n_{ps} for phase separation. The value of n_{ps} is determined by making a cubic polynomial fit to each curve and using the corresponding energy for the lattice full of electrons calculated for the same number of electrons and the same boundary conditions. This latter energy may be estimated from the GFMC results obtained for various size lattices for the square-lattice spin-1/2 Heisenberg antiferromagnet and using the extrapolation¹

$$E/N = e_0 + \lambda N^{-3/2}, \tag{52}$$

where N is the total number of electrons.

FIG. 8. The ground-state energy per site at J=t for $N_e=42$ electrons and $N_s=49,56,64,72,81,90$ sites (bottom curve) $N_e=50$ and $N_s=56,64,72,81,90$ (second from the bottom), and $N_e=60$ and $N_s=64,72,81,90,100,110,121$ sites (top curve). Each curve has been shifted upwards with respect to the previous by 0.025 in order to distinguish them.

The ground-state energy per site at J=t for fixed number of electrons N_e and for various number of sites N_s can be grouped together. The bottom curve in Fig. 8 gives the energy per site as a function of density $n_e = N_e/N_s$ for N_e =42 and $N_s = 49(7\times7)$, 56(7×8), 64(8×8), 72(8×9), 81(9×9), and 90(9×10). The second from the top gives the energy per site shifted by a constant amount of 0.025 for $N_e = 50$ and $N_s = 56$, 64, 72, 81, 90. The third from the top gives the energy per site shifted by an 0.05 for $N_e = 60$ and $N_s = 64$, 72, 81, 90, 100, 110, 121. The unshifted energies are given in Table I. If we plot these curves on the same scale without a shift, they all fall on almost the same curve. However, there are small deviations which are shell effects.

Also shown in Table I is the lowest energy obtained by diagonalizing within the subspace spanned by a subset of 2, 3, or 4 different powers. This is similar to the Lanczos algorithm for quantum Monte Carlo data introduced by Caffarel, Gadea, and Ceperley.⁴⁶ The energies obtained are upper bounds to the ground-state energy.

We can greatly eliminate the shell effects by examining several size lattices but keeping the number of electrons fixed. We first fit each curve generated for fixed N_e with a quartic spline. Next from the point $e(n_e=1)$ on the graph, we construct the tangent to the spline which fits our points. The value of the density at which the tangent and the spline meet gives us an estimate of the phase-separation density for

TABLE I. The energy per site for J/t=1 and for various electrons densities and size lattices. The extrapolation energy is obtained by the procedure described in Sec. III A. The Lanczos energy is the lowest obtained by diagonalization within a subspace of projection powers.

N _e	N_s	n _e	E_{Extrap}/N_s	E_{Lanc}/N_s
32	100	0.32	-0.9019(12)	-0.9008(7)
	81	0.395	-1.0204(34)	-1.0197(47)
	72	0.444	-1.0767(12)	-1.0750(15)
	64	0.5	-1.1249(48)	-1.1220(27)
	56	0.571	-1.1727(48)	-1.1760(72)
	49	0.653	-1.1828(44)	-1.1840(35)
	42	0.762	-1.1853(57)	-1.1801(18)
	36	0.889	-1.1637(40)	-1.1681(29)
42	121	0.347	-0.9463(13)	-0.9448(5)
	100	0.42	-1.0583(38)	-1.0548(39)
	81	0.519	-1.1335(37)	-1.1383(41)
	72	0.583	-1.1562(34)	-1.1548(15)
	64	0.656	-1.1695(18)	-1.1662(22)
	56	0.75	-1.1768(32)	-1.1765(24)
	49	0.857	-1.1674(33)	-1.1656(16)
50	121	0.413	-1.0229(36)	-1.0192(8)
	100	0.5	-1.1080(38)	-1.1022(35)
	90	0.556	-1.1408(49)	-1.1338(32)
	81	0.617	-1.1566(39)	-1.1612(63)
	72	0.694	-1.1766(58)	-1.1741(37)
	64	0.781	-1.1787(89)	-1.1663(38)
	56	0.893	-1.1633(38)	-1.1606(30)
60	110	0.545	-1.1451(40)	-1.1442(35)
	100	0.6	-1.1601(36)	-1.1602(18)
	90	0.667	-1.1698(34)	-1.1697(23)
	81	0.741	-1.1769(28)	-1.1759(41)
	72	0.833	-1.1771(37)	-1.1710(35)
	64	0.938	-1.1628(18)	-1.1612(15)

the given value of J/t. Individually, each number of electrons is consistent with a solution where a line beginning from the no-hole limit $(n_e=1)$ and being tangent on the polynomial (that fits the data points) near $n_e=0.745$ (see Fig. 8). Therefore we conclude that the finite-size effects are small in our method of determining n_{ps} and the phase-separation density for J/t=1 is $n_{ps}=0.745\pm0.015$. Emery, Kivelson, and Lin²⁰ calculated the phase-

Emery, Kivelson, and Lin²⁰ calculated the phaseseparation density using the energy per hole,

$$e_h(x) = \frac{E(N_h) - E(0)}{N_h},$$
 (53)

where $E(N_h)$ is the total energy of the N_s -site system with N_h holes, and $x = N_h/N_s$ is the hole density. In Fig. 9 the energy per hole is plotted for all the points calculated for 42, 50, and 60 electrons. The cubic fits attain minima at approximately the same values as the tangent constructions. The energies in Fig. 9 are not shifted as they are in Fig. 8, and the shell effects are obvious. For each number of electrons, the energy is a smooth function of the density. However, taking all electron numbers together, the energy is a very jagged function: The shell effects systematically bias the energies of systems with a given number of electrons. Therefore it is essential to compare the energies of systems with the same number of electrons, thus canceling the unavoidable systematic errors. Many previous studies of the two-dimensional (2D) t-J model suffered from shell effects. A different demonstration of shell effects is given in Ref. 21.

C. Results in the J < t region

The ground-state energy per site at J=0.5t for fixed number of electrons N_e and for various number of sites N_s can be grouped together. The top curve in Fig. 10 gives the energy per site as a function of density $n_e = N_e/N_s$ for $N_e = 32$ and $N_s = 36(6 \times 6)$, $49(7 \times 7)$, $56(7 \times 8)$, $64(8 \times 8)$, $72(8 \times 9)$, $81(9 \times 9)$, and $90(9 \times 10)$. The second from the top gives the energy per site shifted by a constant amount of 0.05 for N_e



FIG. 9. The energy per hole at J=t for $N_e=42$ (open diamonds), $N_e=50$ (solid squares), and $N_e=60$ (solid circles). The shell effects have nonmonotonic influence on the scaling with size of the energy per hole.



FIG. 10. The ground-state energy per site at J=0.5t for N_e = 32 electrons and N_s =36,49,56,64,72,81,90 sites (top curve), N_e = 42 and N_s =49,56,64,72,81,90 (second from the top), N_e =50 and N_s =56,64,72,81,90 (third from the top), and N_e =60 and N_s = 49,56,64,72,81,90,100,110 sites (bottom curve). Each curve has been shifted downward with the respect to the previous by 0.05 in order to distinguish them.

=42 and N_s =49, 56, 64, 72, 81, 90. The third from the top gives the energy per site shifted by an 0.1 for N_e =50 and N_s =56, 64, 72, 81, 90. The bottom curve gives the energy per site shifted by 0.15 for N_e =60 and N_s =49, 56, 64, 72, 81, 90, 100(10×10), 110(11×10). The unshifted energies are given in Table II.

Here again, we can greatly eliminate the shell effects by examining several size lattices but keeping the number of electrons fixed. We first fit each curve generated for fixed N_{ρ} with a cubic spline where the Heisenberg point has been excluded from the fit. Next we find the point on the graph, where $e_H(N_e)$ is the energy per electron for the Heisenberg antiferromagnet calculated on a finite-size system with the same number of electrons N_e (as discussed previously). Next we construct the tangent to the spline which fits our points. The value of the density at which the line is tangent to the spline gives us an estimate of the phase-separation density for this value of J/t. These values extracted from the different sets of energies which correspond to the same number of electrons are given in Table III. Individually, each number of electrons is consistent with a value of n_{ps} near $n_e = 0.84$ (see Fig. 10). Clearly the 42 electron data do not prove that there is a clear tangent at this value of n_e , but the data are consistent with this value. Therefore we conclude that the finitesize effects are small in our method of determining n_{ps} and the phase-separation density for J/t=0.5 is $n_{ps}=0.843$ $\pm 0.015.$

We wish to demonstrate the significance of shell effects. Let us select from our results of Table II for J/t=0.5 those which correspond to the same size lattice 8×8 for $N_e = 32,42,50,60$. They are shown in Fig. 11. Notice that even though these data also give the same phase-separation density within error bars as that determined by our method described before, the shell effects are large. Such deviations from a smooth curve could lead to drawing the wrong conclusions about phase-separation boundaries.

TABLE II. The energy per site for J/t=0.5 and for various electrons densities and size lattices.

N _e	N_s	n _e	E_{extrap}/N_s	E_{lanc}/N_s
32	64	0.500	-1.0102(19)	-1.0111(18)
	56	0.571	-1.0151(24)	-1.0147(14)
	49	0.653	-0.9811(27)	-0.9802(15)
	42	0.762	-0.8890(33)	-0.8893(32)
	36	0.889	-0.7272(11)	-0.7277(17)
42	100	0.420	-0.9695(22)	-0.9698(21)
	81	0.519	-1.0158(31)	-1.0143(22)
	72	0.583	-1.0115(50)	-1.0030(15)
	64	0.656	-0.9734(32)	-0.9734(22)
	56	0.750	-0.8918(39)	-0.8851(5)
	49	0.857	-0.7715(24)	-0.7733(22)
50	100	0.500	-1.0015(37)	-0.9925(11)
	90	0.556	-0.9975(42)	-1.0009(29)
	81	0.617	-0.9898(54)	-0.9887(68)
	72	0.694	-0.9310(24)	-0.9340(36)
	64	0.781	-0.8594(37)	-0.8565(59)
	56	0.893	-0.7232(22)	-0.7242(15)
52	100	0.520	-1.0090(40)	-1.0102(44)
	90	0.578	-1.0020(58)	-1.0032(80)
	81	0.642	-0.9791(46)	-0.9774(42)
	72	0.722	-0.9110(44)	-0.9107(62)
	64	0.812	-0.8158(29)	-0.8153(20)
	56	0.929	-0.6688(31)	-0.6642(6)
60	110	0.545	-1.0069(33)	-1.0041(15)
	100	0.600	-0.9929(24)	-0.9911(20)
	90	0.667	-0.9676(32)	-0.9687(42)
	81	0.741	-0.8938(11)	-0.8940(12)
	72	0.833	-0.7947(31)	-0.7918(18)
	64	0.938	-0.6623(25)	-0.6605(31)

For completeness in Fig. 12 the energy per hole is given for all the points calculated for 32, 42, 50, and 60 electrons. The curve attains a minimum at approximately the same value as that determined by the tangent construction at the cubic polynomial fit of the energy per size for a given number of electrons. Notice, again, the shell effects.

D. Results near J_c^B

Boninsegni and Manousakis¹⁵ (BM) found a critical value $J_c^B \approx 0.27t$ of J/t below which there is no two-hole *d*-wave bound state. This value of J_c^B was determined by calculating the binding energy for two holes on lattices up to 8×8 . BM noticed that because the bound-state wave function decays exponentially with distance the finite-size effects were rather small. They did, however, pursued a finite-size analysis from which they determined J_c^B . Nevertheless their calculated value of the two-hole binding energy at J/t=0.7 was $\Delta/t = 0.31(03)$, and at J/t=0.4, $\Delta/t=0.12(04)$. Thus we choose the J/t=0.3 to examine the question of phase separation believing that this value is very close to the critical value J_c^B .

TABLE III. The phase-separation density at J/t=0.5 determined by keeping the electron number fixed and varying the lattice size.

n	σ	N _e
0.831 782	0.003 096 39	32
0.838 086	0.013 686 7	42
0.840 684	0.002 381 98	50
0.847 915	0.002 335 89	52
0.857 529	0.009 138 04	60

In Fig. 13 we give the ground-state energy as a function of the electron density for 50, 52, and 60 electrons for J/t = 0.3 as three shifted curves (see Table IV). Notice that the values of J_c/t determined from the these sets of data are very close. We obtain $n_e = 0.877 \pm 0.010$. For J/t = 0.3 in Fig. 14 there is a minimum at $x_{ps} = 0.12$ which agrees very well with the value obtained from the tangent construction.

There are no published GFMC results for the two-hole case for J/t = 0.3. We can obtain an estimate for the single-hole energy by fitting the calculated values for that as a function of J/t to a form $E = E_0 + aJ^{2/3}$. The two-hole binding energy for J/t = 0.3 can be estimated using the formula which was used by Boninsegni and Manousakis¹⁵ to obtain the critical value of J_c^B . Thus, assuming that holes are bound in pairs and they form a dilute gas of hole pairs, we can obtain a value for the energy per hole in such a case. This value of this energy is higher than the value of the energy per hole at the minimum of our curve in Fig. 14. This is another indication that there is more binding energy gained due to the phase separation of the pairs of holes from the electrons in an antiferromagnetically ordered state.

E. Results below J_c^B

Here we examine the situation below the critical value J_c^B for two-hole *d*-wave bound state in the 2D *t-J* model. We shall examine the energy at J/t=0.2. First of all the ground-state energy per site for $N_e=50$ and $N_e=60$ and for various



FIG. 11. The energy per site at J=0.5t for an 8×8 lattice for 32, 42, 50, and 60 electrons.



FIG. 12. The energy per hole at J=0.5t for 32, 42, 50, and 60 electrons.

size lattices is shown in Fig. 15 and is given in Table V. Notice again that the values of J_c/t determined from the two sets of data are very close, we find: $n_{ps} = 0.909 \pm 0.008$.

Below J_c^B where there is no two-hole *d*-wave bound state (assuming there are no bound states in other channels), if there is no phase separation the minimum energy per hole should be the single hole energy at zero hole density. At J/t=0.2 the single hole energy was also calculated by Boninsegni and Manousakis for an 8×8 and 10×10 size lattices. This value of the energy is shown if Fig. 16 and it is clearly higher than the minimum of the energy per hole curve which occurs at approximately hole density of x=0.09.

V. PHASE DIAGRAM OF THE t-J MODEL

In Fig. 17 we present as a function of J/t the minimum energy per hole (solid line) (the minimum of the energy per hole versus density for a given value of J/t). We also plot the single hole energy (obtained by Boninsegni and



FIG. 13. The ground-state energy per site at J=0.3t for 50, 52, and 60 electrons and lattices of sizes $N_s=56,64,72,81,90$, $N_s=56,64,72,81,90$, and $N_s=64,72,81,90$, respectively.

 N_{e} 50

60

TABLE IV. The energy per site for J/t = 0.3 and for various electrons densities and size lattices.

TABLE V. The energy per site for J/t=0.2 and for various electrons densities and size lattices.

N _e	N_s	n _e	E_{extrap}/N_s	E_{lanc}/N_s
50	90	0.556	-0.9494(28)	-0.9469(25)
	81	0.617	-0.9199(37)	-0.9174(23)
	72	0.694	-0.8469(25)	-0.8482(25)
	64	0.781	-0.7381(42)	-0.7419(48)
	56	0.893	-0.5510(13)	-0.5523(15)
52	90	0.578	-0.9407(31)	-0.9372(38)
	81	0.642	-0.9064(41)	-0.9099(48)
	72	0.722	-0.8110(38)	-0.8095(29)
	64	0.812	-0.6881(34)	-0.6852(49)
	56	0.929	-0.4806(18)	-0.4777(9)
60	90	0.667	-0.8814(11)	-0.8815(13)
	81	0.741	-0.8010(13)	-0.7976(23)
	72	0.833	-0.6538(34)	-0.6496(13)
	64	0.938	-0.4640(23)	-0.4615(9)



FIG. 14. The energy per hole at J=0.3t for 50, 52, and 60 electrons.



FIG. 15. The ground-state energy per site at J = 0.2t for 50 and 60 electrons and lattices with sizes $N_s = 56,64,72,81,90$ and N_s = 64,72,81,90, respectively.

N_s	n _e	E_{extrap}/N_s	E_{lanc}/N_s
90	0.556	-0.9246(35)	-0.9211(54)
81	0.617	-0.8905(34)	-0.8822(15)
72	0.694	-0.8103(28)	-0.8098(32)
64	0.781	-0.6825(23)	-0.6826(27)
56	0.893	-0.4681(18)	-0.4717(23)
90	0.667	-0.8426(32)	-0.8414(14)
81	0.741	-0.7419(24)	-0.7432(17)
72	0.833	-0.5857(23)	-0.5853(31)

-0.3701(17)

0.938

64



FIG. 16. The energy per hole at J = 0.2t for 50 and 60 electrons. The single hole energy as obtained from Boninsegni and Manousakis is also plotted for 8×8 and 10×10 size lattices.



FIG. 17. The energy per hole at the density where the phaseseparation separation minimum occurs as a function of J/t (solid line). This is compared to the energy per hole obtained from the single hole calculation of Boninsegni and Manousakis (1992) (dashed line) and to the energy per hole obtained from the two-hole calculation of Boninsegni and Manousakis (1993).

-0.3693(7)

Manousakis¹⁶) as a function of J/t which is the energy per hole in the case of isolated noninteracting holes in the system (dashed line). In addition, the energy per hole is compared with the energy per hole obtained by Boninsegni and Manousakis¹⁵ from calculation of two holes in the *t*-*J* model. The energy per hole in this latter calculation gives the energy per hole in the case of isolated bound hole pairs (dotted line). Notice that while the dashed line and the dotted line meet at $J/t \sim 0.3$, the minimum at the phase-separation density and the dotted line do not meet. Notice that the additional energy gained to phase separation decreases with decreasing J/t as expected.

In Fig. 18 we show the phase-separation boundary obtained for all values of J/t using the method described in the present paper and the Maxwell construction. In Table VI we give the phase-separation boundary as determined for various values of J/t from the various size lattices and number of electrons.

A more complete phase diagram for the 2D *t-J* model as a function of J/t and doping was given in Fig. 3 of Ref. 17. That phase diagram is also accurate in the low-density region where exact calculations can be done.¹⁴

VI. COMPARISON WITH OTHER CALCULATIONS

In Fig. 19, our phase diagram is compared to the recent fixed node Monte Carlo calculations of Callandra, Becca, and Sorella²⁷ (CBS) and to the high-temperature series expansion calculations of Putikka, Luchini, and Rice.²⁴ Notice that our phase diagram and that of CBS are very close except in the delicate physical region of small J/t. Therefore we can draw a relatively strong conclusion from this comparison: The findings drawn from the early studies of the *t-J* model that the physical region of the model is safely away from the phase-separation boundary are not correct. What our work and the work of CBS find is that the interesting region of J/t is either next to the phase-separation boundary or inside the phase separated region. In both cases phase-separation fluctuations could play an important role in the mechanism for superconductivity in the copper oxides.



FIG. 18. The phase-separation boundary as calculated using the present method and the Maxwell construction.

TABLE VI. The phase-separation boundary as calculated using
the present method. The last value with $n = 0$ is derived analytically
in Ref. 14.

J	n	σ
0.1	0.9484	0.017
0.2	0.909	0.008
0.3	0.877	0.010
0.5	0.845	0.015
1.0	0.730	0.016
1.25	0.624	0.010
1.5	0.568	0.027
2.0	0.439	0.008
2.5	0.296	0.004
3.0	0.145	0.0016
3.25	0.0662	0.0006
3.4367	0	0

There is an important difference between our results and those of CBS. Our results indicate that phase separation in the *t*-J model is present for all J/t, while the conclusion of CBS is that there is a finite value of $J \simeq 0.4t$ below which there is no phase separation. The reason for this disagreement is that this region requires a very high degree of accuracy in the numerical results. We would like to discuss the results of CBS where they claim that at J/t = 0.4 there is no phase separation for lattices of size $N_s = 98$. In Fig. 20 we plot the results of CBS for this value of J/t for 50 sites (solid circles) and 98 sites (open squares). The result for the lowest value of x for the 98-site system was not included in the original publication by CBS. CBS were kind enough to calculate it at our request and to communicate it to us. Without using that point, CBS concluded that the fact that we found PS at J/t = 0.4 was a finite-size effect because the energy per site in their largest size system had no minimum. With the most recently calculated point for the 98-site system, $e_h(x)$ has a minimum at $x_c \approx 0.072$. This is close to our value of about $x_c \approx 0.1$ for J/t = 0.4.



FIG. 19. Comparison of our phase-separation boundary with that of Putikka *et al.* (Ref. 24) and of CBS (Ref. 27).



FIG. 20. Quadratic fits of the results obtained by CBS (Ref. 27) for systems with 50 sites (solid circles) and 98 sites (open squares) to a quadratic polynomial. The result for the lowest value of x for the 98-site system was not included in the original publication by CBS.

Let us now examine more specifically the results in Fig. 20. We have labeled by 2, 4, and 6 the points which correspond to 2, 4, and 6 holes in the 50- and 98-site lattices. Notice that the energy of four holes is the same within error bars in both lattices. The same is true for the six hole case. Thus the energy for 2, 4, and 6 holes *seems* to be independent of the size of the lattice within error bars. This can be a either (i) a genuine characteristic of presence of phase separation where the two, four, and six hole bubbles in a much larger system do not feel the size effects because they are self bound at a characteristic size much smaller than the total system or (ii) a result of shell-effects which we have discussed and are minimized in our calculation or (iii) the calculation of CBS has larger systematic or statistical errors than those reflected by their error bars.

White and Scalapino (WS) calculated the energy per hole on systems with cylindrical boundary conditions, that is, systems with open boundaries in one direction of the lattice and periodic in the other.^{28,29,47} They estimate the energy per hole, Eq. (53), by comparing the energy of a system with holes to the energy of the same system with no holes. In Ref. 47, WS argue that their approach is more accurate than that obtained by other methods simply because it gives a lower energy per hole. However, the energy per hole calculated in this way on systems with open boundary conditions is not variational and, as shown below, can artificially *underestimate* the energy per hole.

Systems with open boundary conditions can be made from fully periodic systems by removing a row of bonds. Clearly this process disrupts the periodic ground state and raises the energy.⁴⁸ Both the energy of the system with N_h holes, $E(N_h)$, and the energy of the system with no holes, E(0), increase with open boundary conditions, but generally not by the same amount. The system with holes has more degrees of freedom than the no-hole system, allowing it to respond more effectively to the broken bonds. For example, a system with holes has freedom to twist the antiferromagnetic order parameter at the boundary required by certain



FIG. 21. A two-dimensional stripe-type phase separated state. State (b) has a pi-phase shift which accommodates the hole motion along the stripe but frustrates the antiferromagnetic order in the case of periodic boundary conditions. In state (b) this twist of the order parameter has no magnetic energy cost with open boundary conditions along the *x* direction. Thus periodic BC conditions in this case frustrate either the hole motion along the "stripe" [state (a)] or the antiferromagnetic state [state (b)] along the boundary bonds.

phase separated states. An example of such a state is a single "stripe" shown in Fig. 21. In this example, a striped or structured phase separated state is stabilized in the middle of the system.

Thus one expects that the energy per hole obtained with open boundary conditions (using as a reference state the nohole energy with open boundary conditions) can be lower than the exact energy per hole obtained with periodic boundary conditions (using as a reference state the no-hole energy with periodic boundary conditions).

In Fig. 22, we compare the results of various calculations on similar size lattices for the energy per hole for 1, 2, 4 holes and at our phase-separation minimum. The results for one and two holes are taken from the work of Boninsegni and Manousakis (BM).^{16,15} The finite-size effects are smaller than the size of the symbols. In addition, the result for two holes for a 50-site cluster reported by CBS (Ref. 27) for J/t = 0.4 is shown as an open square. Notice the agreement between BM and CBS (both used periodic boundary conditions). The value for the single hole energy obtained by WS is systematically lower than the value for the periodic lattice. The cylindrical boundary conditions used by WS frustrate the no-hole state, and, as a result, the energy of the no-hole state obtained by WS is much higher than that used by HM and CBS. WS's calculation gives a total energy of E(0) =-35.66 (in units of t and here J/t=0.5) for the no-hole state on the 8×8 lattice, while for a periodic 8×8 lattice the energy which we (and CBS) use is much lower, E(0) =-37.56. WS's total energy for four electrons in a 8×8 lattice is $E(4) = -41.028 \pm 0.075$, while we find E(4) = -42.23 ± 0.12 on a periodic lattice. Thus WS obtain a value for the energy per hole $e_h(4) = -1.34$, while our result corresponds to $e_h(4) = -1.17 \pm 0.03$.

Qualitatively similar conclusions can be drawn for the case of a single hole. The results of BM for a single are shown by the dashed line in Fig. 22. Clearly, WS's single-hole energies are below those also. This lowering of the energy can only be understood by the frustrating effect of open boundary on the antiferromagnetic state.



FIG. 22. Comparison of the energy per hole $e_h(N_h)$ at $N_h=1, 2$, and 4 holes and at the phase-separation minimum. The dashed, dotted, and solid lines are polynomial fits to $e_h(N_h=1)$ from BM, $e_h(N_h=2)$ from BM, and e_h at the phase-separation minimum from HM. Notice that because of the cylindrical boundary conditions which frustrates the no-hole state, WS tend to get more lowering of the energy when they introduce holes. For these size lattices the finite-size effects on the one and two hole calculations are smaller than the symbol size. For comparison we have also placed the result of CBS for two holes in a 50-site lattice which is available for J/t= 0.4. Notice that the CBS and BM results are nearly identical.

Finally notice the very small difference between the energy per hole in the two hole case and in the four hole case obtained by WS at J/t=0.35. They find $e_h(2) = -1.72$ and energy per hole for a stripe -1.737 at the optimum doping of four holes per stripe. The difference is very small and suggests that the WS striped state is only a manifestation of frustrated phase separation.

VII. CONCLUSIONS

We have developed an efficient Green's-function Monte Carlo method for fermions on a lattice that iteratively projects out the ground state with no approximations. Fermionic minus-sign fluctuations are controlled by using all powers of the projection operator up to some maximum and extrapolating to infinite power. Starting from a good initial state allows us to converge before the statistical errors become too large. This technique comes also with solutions to a number of other technical problems such as (i) enabling the guided random walk to walk through the nodes with an $O(N^2)$ algorithm using the idea of a "detour walk;" (ii) using a single walker to compute all the desired powers of projection operator $(H-W)^m$, where the т $=0,1,\ldots,p_{max}$, simultaneously.

This technique is applied to the two-dimensional t-J model to investigate its phase diagram. It is found, contrary to many previous studies that there is phase separation (PS) at all interaction strengths of the t-J model. The signal for phase separation is clear when one overcomes the following difficulties.

First, the Maxwell construction is the cleanest and strongest signal for PS because it suffers the least from finite-size effects. Second the shell effects can mask the signal because the energy as a function of density of different numbers of electrons on a fixed lattice is not a smooth curve. The kinetic energy jumps discontinuously as electrons are added to successive shells. Therefore we have chosen to keep the electron number fixed at a closed-shell configuration and to change the size of the lattice. The number of electrons which form closed-shell configurations depends on the boundary conditions. To generate as many as possible "magic numbers" of closed-shell configurations we have used four types of boundary conditions. Periodic with 0 or π phase shifts at the boundary in each of the \hat{x} and \hat{y} directions.

We find that for any value of J/t the energy per site $e(n_e)$ as a function of electron density n_e for finite-size lattices does not remain a concave function at high electron density. There is a value of the density $n_{ps}(J/t)$ where a straight line starting from the no-hole energy per site is tangent to the curve $e(n_e)$ at $n_e = n_{ps}$. While the energy $e(n_e < n_{ps})$ does not change significantly with system size, the energy of a finite system in the phase-separated regime $e(n_e > n_{ps})$ changes with system size and approaches this tangent line in the infinite-size limit. We interpret this as evidence for phase separation at all values of J/t. The fact that the function $e(n_e)$ does not remain concave in our calculation above $n_{ps}(J/t)$ can be explained by the energy cost of forming an interface between the two phases in our finite system.

Our results have been compared to the most works of Calandra, Becca, and Sorella,²⁷ and we find very close agreement. These comparisons indicate that the early conclusions that the critical J_c/t for phase separation is far away from the physical value of J/t are largely invalid. This comparison also indicates that J_c/t is very small and may vanish. We discuss recent comparison by White and Scalapino⁴⁷ (WS) of our numerical results to theirs. In that comparison, WS use the variational principle to argue that their results are more accurate because the energy per hole in lower. However, we demonstrate that one should expect the exact energy per hole on *periodic lattices* to be higher than that obtained with the cylindrical boundary conditions used by WS. Thus on such different systems, a lower energy cannot be used as a criterion for the accuracy of an approach. In addition, we interpret the results of WS as evidence for phase separation and the appearance of stripes in the t-J model as a finite-size effect.

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APPENDIX A: INVERSE UPDATE THROUGH NODES

To evaluate the determinant in the trial state, we use the usual "inverse update" trick first applied to condensedmatter systems by Ceperley, Chester, and Kalos.⁴¹ We calculate the determinant and inverse of the matrix (26) together at the start of each run, an operation taking $O(N^3)$ steps for a $N \times N$ determinant. Then with each single-particle move in the random walk, we update the determinant in O(N) steps and the inverse in $O(N^2)$ steps.

Starting with the matrix **D** and its inverse **I**, suppose we change row l of the matrix to $D_{lj} \rightarrow r_j$. Since the inverse is the transpose of the matrix of cofactors normalized by the determinant

$$I_{ij} = \operatorname{cof}_{ji}(\mathbf{D}) / |\mathbf{D}|, \qquad (A1)$$

the ratio of the determinant of \mathbf{D} before and after the change is

$$q \equiv \frac{|\mathbf{D}'|}{|\mathbf{D}|} = \sum_{j} r_{j} I_{jl} \,. \tag{A2}$$

The new inverse matrix is given by

$$I'_{ij} = I_{ij} \left(1 + \frac{1}{q} \,\delta_{lj} \right) - \frac{1}{q} I_{il} \sum_{k} r_k I_{kj} \,, \tag{A3}$$

and one can easily confirm $\sum_j D'_{ij}I'_{jk} = \delta_{ik}$. Changing one column of the matrix results in a similar update for the inverse.

The algorithm is straight forward, and has been used in many GFMC studies in the continuum and in variational Monte Carlo on a lattice. *However, it cannot be used directly* with GFMC on a lattice since the random walk steps directly on nodes for a significant fraction of steps. When the matrix becomes singular, its inverse is undefined, and the algorithm breaks down.

One way around this problem is to recalculate the determinant and inverse after walking through a node. However, in a reasonably dense system, a large faction of steps will land on nodes, and the running time will scale as $O(N^3)$.

We developed a different $O(N^2)$ technique to hop over nodes without recalculation of the determinant or inverse. The essence of the method is this: Let us suppose that the random walk visits a node; namely, the particles were in a configuration $\vec{R} = (\vec{r}_{1\uparrow}, \vec{r}_{2\uparrow}, \dots, \vec{r}_{N/2\uparrow}, \vec{r}_{1\downarrow}, \vec{r}_{2\downarrow}, \dots, \vec{r}_{N/2\downarrow})$ and by moving a particle, say the first up-spin particle from position $r_{1\uparrow}$ to $r'_{1\uparrow}$ the determinant defined by Eq. (26) is zero for the new configuration $\vec{R}' = (\vec{r}'_{1\uparrow}, \vec{r}_{2\uparrow}, \dots, \vec{r}_{N/2\uparrow}, \vec{r}_{1\downarrow}, \vec{r}_{2\downarrow}, \dots, \vec{r}_{N/2\downarrow})$. That is a problem for the application of the inverse update. In order to move to the next configuration, say where particle 2 is positioned at $\vec{r}'_{2\uparrow}$ and this corresponds to a new configuration $\vec{R}'' = (\vec{r}'_{1\uparrow}, \vec{r}'_{2\uparrow}, \dots, \vec{r}_{N/2\uparrow}, \vec{r}_{1\downarrow}, \vec{r}_{2\downarrow}, \dots, \vec{r}_{N\downarrow})$, we need the inverse matrix $\mathbf{I} = \mathbf{I}(\mathbf{\vec{R}}')$ for the configuration $\mathbf{\vec{R}}'$ and this does not exist because the determinant $D(\vec{R}')=0$. The nonexistence of the inverse is no problem for the physics because all we need for computing the observables is the determinant, not the inverse; the inverse matrix is only a tool which saves us from having to recalculate the full determinant at each step. We have been able to use the inverse update technique by making a "detour" around the node as follows. The real motion of the random walk was $\vec{R} \rightarrow \vec{R}' \rightarrow \vec{R}''$ and because $D(\vec{R}') = 0$ we cannot update the inverse to find $I(\vec{R}')$ which we need in order to calculate $D(\vec{R}'')$. However, all we need is $D(\vec{R}'')$ and $I(\vec{R}'')$ independently of how the random walk got there. Let us consider the configuration $\vec{R}'_2 = (\vec{r}_{1\uparrow}, \vec{r}'_{2\uparrow}, \ldots, \vec{r}_{N/2\uparrow}, \vec{r}_{1\downarrow}, \vec{r}_{2\downarrow}, \ldots, \vec{r}_{N\downarrow})$, which is obtained from \vec{R} by imagining that we moved (without actually doing it) particle 2 with spin-up to $\vec{r}'_{2\uparrow}$ and let us assume that $D(\vec{R}'_2) \neq 0$. Since \vec{R}'' can be obtained from \vec{R}'_2 by moving particle 1 to $\vec{r}'_{1\uparrow}, D(\vec{R}'')$ and $I(\vec{R}'')$ can be obtained by imagining that the walk went through \vec{R}'_2 to get to \vec{R}'' . Thus, in order to calculate $D(\vec{R}'')$ and $I(\vec{R}'')$ we only need to calculate $D(\vec{R}'_2)$ and $I(\vec{R}'')$ which both exist.

When the random walk generated by the guiding function hits a state or series of states where the determinant of the trial function vanishes, we generate a 'detour' walk around the region where the matrix is singular, rejoining the guiding walk when the determinant is nonzero again.

To choose the detour walk, we simply delay any move causing the determinant to vanish and place the particle number and its future site at the beginning of a list of moves to make. For any subsequent move of a particle of the same spin, we try to move the first particle in the list to that site. If that move yields a nonzero determinant, we accept it and attempt to move the next particle in the list in the same manner. We repeat the process until either all moves give zero determinant or the list is empty, in which case the true determinant is not zero.

Obviously, the procedure will not produce a nonzero determinant when the true determinant is zero. However, it is important to prove that the detour rejoins the guiding walk at the first step with nonzero determinant.

We represent the rows of the matrix (26) by $\mathbf{D} = \{|\mathbf{r}_1\rangle, |\mathbf{r}_2\rangle, \dots, |\mathbf{r}_n\rangle\}$ where $|\vec{r_i}\rangle$ represents the row

$$|\vec{r}_i\rangle = [a(\vec{r}_{i\uparrow} - \vec{r}_{1\downarrow}), a(\vec{r}_{i\uparrow} - \vec{r}_{2\downarrow}), \dots, a(\vec{r}_{i\uparrow} - \vec{r}_{N/2\downarrow})]$$
(A4)

which is labeled by r_i . Suppose moving the first up particle to a new site, changing the first row label to $\mathbf{r}_1 \rightarrow \mathbf{s}$, yields a zero determinant. Then

$$|\mathbf{s}\rangle = \alpha_2 |\mathbf{r}_2\rangle + \alpha_3 |\mathbf{r}_3\rangle + \dots + \alpha_n |\mathbf{r}_n\rangle$$
(A5)

for some coefficients $\alpha_2, \alpha_3, \ldots, \alpha_n$. Let the next random walk step move the second particle, changing row $\mathbf{r}_2 \rightarrow \mathbf{t}$. Simply by checking if the matrix $\mathbf{D}' = \{|\mathbf{t}\rangle, |\mathbf{r}_2\rangle, \ldots, |\mathbf{r}_n\rangle\}$ has zero determinant, we can determine if the true matrix $\mathbf{D}'' = \{|\mathbf{s}\rangle, |\mathbf{t}\rangle, |\mathbf{r}_3\rangle, \ldots, |\mathbf{r}_n\rangle\}$ is singular. If $|\mathbf{D}'| \neq 0$, we accept the move, swap the particles, and try to move the first particle again. If $|\mathbf{D}'| = 0$,

$$|\mathbf{t}\rangle = \beta_2 |\mathbf{r}_2\rangle + \beta_3 |\mathbf{r}_3\rangle + \dots + \beta_n |\mathbf{r}_n\rangle$$
(A6)

for certain coefficients $\beta_2, \beta_3, \ldots, \beta_n$. Combining Eqs. (A5) and (A6) to eliminate \mathbf{r}_2 , we see that $|\mathbf{D}'|=0$ implies $|\mathbf{D}''|=0$. Thus by simply checking single-particle moves, we can verify that the determinant of the matrix two steps away is zero. The argument is easily generalized to any number of delayed moves.

For a Fermi-liquid state, Eq. (26) may be expanded into the product of two Slater determinants, and this algorithm suffices as it stands. However, with a pairing trial state, this decomposition is not possible, we must consider moves of opposite spin electrons causing the determinant to vanish.

Suppose we find moving either the first up particle, changing the first row to $D_{1j} \rightarrow r_j$, or the first down particle, changing the first column to $D_{i1} \rightarrow c_i$, results in a zero determinant for matrix (26).

If $I_{11} \neq 0$ we move the first row with the first element shifted by $1/I_{11}$, noting

$$|\mathbf{D}'| = \begin{vmatrix} r_1 + \frac{1}{I_{11}} & r_2 & \cdots & r_n \\ D_{21} & D_{22} & \cdots & D_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ D_{n1} & D_{n2} & \cdots & D_{nn} \end{vmatrix} = |\mathbf{D}|.$$
(A7)

We then try to change the first column in the standard manner. We have artificially changed the upper-left element of the determinant, but since this element will be changed again before we finish the detour walk, the change will not affect the true determinant.

If $I_{11}=0$, this modified step is no longer possible, and we need to prove that the true determinant,

$$|\mathbf{D}''| = \begin{vmatrix} x & r_2 & \cdots & r_n \\ c_2 & D_{22} & \cdots & D_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_n & D_{n2} & \cdots & D_{nn} \end{vmatrix} = 0,$$
(A8)

vanishes. Here x is the upper-left element after both moves.

We know there exist coefficients $\alpha_2, \alpha_3, \ldots, \alpha_n$ such that $r_j = \sum_{i \ge 2} \alpha_i d_{ij}$ for all *j*. Since the inverse is related to the matrix of cofactors by Eq. (A1), $cof_{11}(\mathbf{D}) = 0$, and there are other coefficients $\beta_2, \beta_3, \ldots, \beta_n$ such that $0 = \sum_{i \ge 2} \beta_i d_{ij}$ for all $j \ge 2$. If $\sum_{i \ge 2} \beta_i c_i = 0$, then $|\mathbf{D}''| = 0$ trivially. Otherwise let $\gamma_i = \alpha_i + \lambda \beta_i$ where

$$\lambda = \left(x - \sum_{i \ge 2} \alpha_i c_i \right) / \sum_{i \ge 2} \beta_i c_i .$$
 (A9)

Then $x = \sum_{i \ge 2} \gamma_i c_i$ and $r_j = \sum_{i \ge 2} \gamma_i d_{ij}$ for all $j \ge 2$, so $|\mathbf{D}''| = 0$.

Again, this argument can be extended to any number of delayed moves. By combining the two types of moves described in this section, we are able to keep track of the true determinant without recalculating the inverse from scratch.

APPENDIX B: O(N) CALCULATION OF SUPEREXCHANGE

For a determinantal function, the kinetic terms in Eq. (33) require O(N) steps per particle, so it scales as $O(N^2)$ for the system. The superexchange term in the *t*-*J* model, $\sum_{\langle i,j \rangle} S_i^+ S_j^-$, exchanges two particles, changing both a row and a column of the determinant (26). In this section, we show how the amplitude of swapping two particles may be calculated in O(N) steps.

Suppose we swap the *m*th up electron with the *n*th down electron. We will modify both row *m* and column *n* in the determinant. We write the new elements as $D_{mj} \rightarrow r_j$ and $D_{in} \rightarrow c_i$. Naturally, $r_n = c_m$. One can show the ratio of the determinant before and after the swap is

$$\frac{|\mathbf{D}'|}{|\mathbf{D}|} = \left(\sum_{i} r_{i} I_{im}\right) \left(\sum_{j} I_{nj} c_{j}\right) + I_{nm} c_{m} - I_{nm} \sum_{i,j} r_{i} I_{ij} c_{j}.$$
(B1)

Direct evaluation of the sum $S = \sum_{i,j} r_i I_{ij} c_j$ takes $O(N^2)$ per pair of neighboring particles. For this reason, many researchers evaluate the superexchange term only every N Monte Carlo steps.³⁸

Our trick is to evaluate *S* once when a pair of particles become nearest neighbors, and then to update it in O(N)steps for any move not disrupting the pair. Suppose the *l*th up electron moves $(l \neq m)$, altering row *l* in the determinant (26), so $D_{lj} \rightarrow s_j$. The inverse *I* is updated according to Eq. (A3) and $c_l \rightarrow c'_l$ takes a new value.

We can write the new sum S' in terms of the old sum and extra factors as

$$S' = \sum_{i,j} r_i I'_{ij} c'_j$$

= $\sum_{i,j} r_i \left(I_{ij} \left(1 + \frac{1}{\gamma_l} \delta_{lj} \right) - \frac{1}{\gamma_l} I_{il} \sum_k s_k I_{kj} \right) c'_j$
= $S + \frac{1}{\gamma_l} \left(\sum_i r_i I_{il} \right) \left(c'_l - \sum_j \gamma_j c_j \right),$ (B2)

where $\gamma_j = \sum_k s_k I_{kj}$ is used in the inverse update. This calculation requires only O(N) steps, so the local superexchange energy of the system may be evaluated in $O(N^2)$ time.

APPENDIX C: ENERGY AT THE PHASE-SEPARATION BOUNDARY

In the phase-separated state, the t-J model separates into two phases, one with all electrons (no holes) and the other with some electrons and some holes. The transition is continuous: As J is increased in the phase-separated regime, the electron density in the low-electron-density phase decreases while the proportion of Heisenberg phase increases. The energy in the partially phase separated regime is simply the weighted sum of the two constituent energies. Specifically, the energy of the phase separated state is given by

$$E_{ps}(n,J) = \frac{1-n}{1-n_{ps}} E_u(n_{ps},J) + \frac{n-n_{ps}}{1-n_{ps}} E_H J, \quad (C1)$$

where $E_u(n,J)$ is the energy of the uniform density phase as a function of electron density and interaction strength, E_HJ is the energy of the Heisenberg phase, and $n_{ps}(J)$ is the density of the onset of phase separation.

Across the phase-separation boundary, the energy is continuous as is its first derivative with respect to density. Using this fact, we can show that the derivative of the energy in the phase-separated regime with respect to J is given by

$$\frac{\partial E_{ps}(n,J)}{\partial J} = \frac{1-n}{1-n_{ps}} \frac{\partial E_u(n_{ps},J)}{\partial J} + \frac{n-n_{ps}}{1-n_{ps}} E_H \quad (C2)$$

so the first derivative of the energy with respect to J is continuous at the phase-separation point, $n = n_{ps}(J)$. All terms of the form $\partial n_{ps}(J)/\partial J$ are canceled from this expression. Note that for $J > J_c$, where J_c is the critical interaction strength for complete phase separation, $n_{ps}(J \ge J_c) = 0$ and $E_u(n=0,J)=0$.

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